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Experiment, Theory, and the Hypersonic Isolation Principle

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Aerodynamic Characteristics of a Distinct Wing-Body Configuration at Mach 6

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Scientific and Technical Information Branch

Summary

An experimental wind-tunnel investigation has been conducted to determine the effect of wing leading-edge sweep and wing translation on the aerodynamic characteristics of a wing-body configuration at a free-stream Mach number of about 6 and a freestream Reynolds number (based on body length) of 17.9×10^6 . Seven wings with leading-edge sweep angles from -30° to 60° were tested on a common body in a blowdown tunnel over an angle-of-attack range from -12° to 10° at angles of sideslip of 0° and 2°. All wings had a common span, aspect ratio, taper ratio, planform area, and thickness ratio. The wings were translated longitudinally on the body to make tests possible with the total and exposed mean aerodynamic chords located at a fixed body station. Aerodynamic forces were found to be independent of wing sweep and translation, and pitching moments were constant when the exposed wing mean aerodynamic chord was located at a fixed body station. Thus, the "Hypersonic Isolation Principle" was verified. Impact theory applied with tangentwedge pressures on the wing and tangent-cone pressures on the body provided excellent predictions of aerodynamic force coefficients but poor estimates of moment coefficients.

Introduction

The design of an efficient hypersonic cruise aircraft requires a detailed knowledge of how various geometrical parameters affect the longitudinal and lateral aerodynamic characteristics of the complete aircraft. One important geometrical parameter is wing leading-edge sweep. Many wind-tunnel test programs have previously been performed to study the effect of wing sweep on performance, stability, and control, particularly in the speed range from high subsonic to low supersonic Mach numbers (ref. 1). Studies at hypersonic speeds have dealt primarily with the aerodynamics of specific configurations of various geometries with emphasis on delta wings, aerodynamic heating, particularly of blunt leading edges, and comparisons of experiment with theory. Few studies at hypersonic speeds have tested configurations having variations in wing leading-edge sweep while holding other geometric parameters constant. References 2 to 9 represent some exceptions at Mach numbers of about 3 to 7.

One objective of the study reported herein was to determine for Mach 6 a procedure for systematically varying the wing leading-edge sweep angle of a distinct wing-body configuration so that the longitudinal force and moment characteristics would remain constant. Seven wings with different leading-edge sweep angles but with constant span, aspect ratio, taper ratio, planform area, and thickness ratio were investigated. The mean aerodynamic chord \bar{c} was constant and the location of \bar{c} relative to the longitudinal body station was constant for all tests.

Another objective was to determine whether to base \bar{c} on the exposed or wetted wing area or on the total wing area, including that wing area which falls inside the fuselage. The mean aerodynamic chord based on the exposed wing area is supported by what we propose to call the "Hypersonic Isolation Principle," that is, that aerodynamic forces are generated only by those components exposed to the hypersonic flow, that aerodynamic forces act at the centroid of the planform of the components, and that component interference is virtually negligible. These principle assumptions are made in most impact theory aerodynamic computer codes.

Tests were conducted in the Langley 20-Inch Mach 6 Tunnel at a free-stream Reynolds number of 17.9×10^6 based on body length for an angle-of-attack range of approximately -12° to 10° . Seven different wings with leading-edge sweep angles that varied from -30° (forward sweep) to 60° (rearward sweep) in 15° increments were tested. The test configuration was constructed so that each wing could be tested with the exposed mean aerodynamic chord and the total mean aerodynamic chord at separate but fixed body stations. A theoretical study using hypersonic impact methods was also conducted and reported herein.

Symbols

The longitudinal characteristics are presented about the stability axes, and the lateral-directional characteristics are presented about the body axes. The moment reference point was at the design center-of-gravity location, which was at a longitudinal station 62.2 percent of the fuselage length and at a vertical station 1.12 percent of the fuselage length below the vehicle reference line.

\boldsymbol{A}	reference area (total area of all wings, including body intercept), 76.3812 in ² (see fig. 1)
AR	aspect ratio
\boldsymbol{b}	wing span, 12.60 in.
C_A	axial-force coefficient, $\frac{F_A}{q_{\infty}A}$
C_D	drag coefficient, $\frac{D}{q_{\infty}A}$
C_F	average skin-friction coefficient, compressible

C_L	lift coefficient, $\frac{L}{q_{\infty}A}$	M	local Mach number				
C_l	rolling-moment coefficient,	M_{∞}	free-stream Mach number				
	$\frac{M_X}{q_{\infty}Ab}$	M_X, M_Y, M_Z	moments about X -, Y -, and Z -axes				
$C_{oldsymbol{l}_{oldsymbol{eta}}}$	rate of change of C_l with angle of sideslip, per degree	p_{∞}	free-stream static pressure				
$C_{m{m}}$	pitching-moment coefficient,	q_{∞}	free-stream dynamic pressure				
	$rac{M_Y}{q_{\infty}Aar{c}_{ ext{tot}}}$	R	local Reynolds number				
C_N	normal-force coefficient, $\frac{F_N}{q_{\infty}A}$	R_l	Reynolds number based on fuselage length				
C_n	yawing-moment coefficient,	r_1	top body radius				
	$\frac{M_Z}{q_{\infty}Ab}$	r_2	bottom body edge radius				
$C_{m{n}_{m{eta}}}$	rate of change of C_n with angle of sideslip, per degree	T.E.	trailing edge				
$C \sim c$	70 percent vacuum condition $\left(C_{p, \text{limit}} = -\frac{1}{M_{\infty}^2}\right)$	T_t	total or stagnation temperature				
$C_{p, m limit}$		$T_{m{w}}$	wall temperature				
		t	airfoil thickness				
C_Y	side-force coefficient, $\frac{F_Y}{q_{\infty}A}$	X,Y,Z	reference axes				
$C_{Y_{oldsymbol{eta}}}$	rate of change of C_Y with angle of sideslip, per degree	x_{cp}	distance from leading edge of \bar{c} to center of pressure				
c	local chord	ΔZ	droop of body nose (see fig. 1)				
$ar{c}$	mean aerodynamic chord	α	angle of attack, deg				
$ar{c}_{ ext{exp}}$	mean aerodynamic chord based on exposed wing outside	Λ	angle of leading-edge sweep, deg				
_	of body		taper ratio, Tip chord/Root chord				
$ar{c}_{ ext{tot}}$	mean aerodynamic chord based on total wing area, including body intercept	Models, Appa	paratus, and Tests				
D	drag, $F_N \sin \alpha + F_A \cos \alpha$	Test Configurations					
diam	diameter diameter	The geometric details and photograph of the configurations are shown in figures 1, 2, and 3;					
F_{A}	axial force along X -axis (positive direction is $-X$)	nose dimensions are listed in table I. The b figuration consisted of a body and a series					
F_N	normal force along Z -axis (positive direction is $-Z$)	interchangeable wings with constant span, planarea, aspect ratio, taper ratio, thickness ratio streamwise root and tip chords. (See table II					

 st lу nn m area, aspect ratio, taper ratio, thickness ratio, and streamwise root and tip chords. (See table II.) All wings had 3-percent-thick symmetrical wedge-slabwedge airfoil sections with 0.006-in. leading and trailing edges (fig. 1). The leading-edge sweep angles were varied from -30° (forward sweep) to 60° (rearward sweep) in 15° increments. In the interest of economy, the 60° swept wing was designed to be reversed on the body and was thus tested as the -30° swept wing. Also, the body was designed to allow the wings to be tested at two different longitudinal locations. The exact longitudinal location of each test wing was determined by two factors. The first was the location

l

 F_{Y}

h

L

L.E.

L/D

side force along Y-axis (posi-

height of body (see fig. 1)

lift, $F_N \cos \alpha - F_A \sin \alpha$

length of model fuselage,

leading edge

lift-drag ratio

28.03 in.

tive direction is -Y)

of the exposed mean aerodynamic chord of the 60° -swept-wing baseline configuration based on that portion of the exposed wing extending from the fuselage side to the wing tip $\bar{c}_{\rm exp}$. The second factor was the location of the total wing mean aerodynamic chord of the 60° swept wing based on the total wing area, including that area covered by the body intercept $\bar{c}_{\rm tot}$. The moment reference was located longitudinally at 25 percent of $\bar{c}_{\rm tot}$ and vertically at the centroid of the fuselage cross section.

The nose contour was designed by using tangent cone theory such that $C_N = 0$ at $\alpha = 0^{\circ}$. Thus, the listing of nose droop ΔZ is included in table I (fig. 1).

Apparatus and Tests

This investigation was conducted in the Langley 20-Inch Mach 6 Tunnel. The tunnel operates on a blowdown cycle through a two-dimensional nozzle with a test section 20.5 in. high and 20 in. wide. Dry air was used for all tests to avoid water condensation effects, and the air was heated to avoid air liquefaction. Tests were conducted at an average free-stream Mach number of 5.98, a stagnation pressure of about 440 psia, and a stagnation temperature of about 870°R. These conditions result in an average free-stream Reynolds number based on fuselage length of about 17.9×10^6 (7.66 $\times 10^6$ per foot, or 4.34×10^6 based on \bar{c}_{tot}).

A six-component water-cooled strain-gage balance was installed inside the model body and was attached to the tunnel variable-angle sting support system. Forces and moments were measured through an angle-of-attack range of -12° to 10° and at angles of sideslip of 0° and 2° . All screw and dowel holes and joints were filled with dental plaster before each test run. Base pressures were measured, and the axial-force component was adjusted to correspond to a base pressure equal to the free-stream static pressure. All tests were conducted with natural boundary-layer transition.

Theoretical Methods

Theoretical estimates for this study were made primarily through the use of the Mark III Gentry Hypersonic Arbitrary-Body Aerodynamic Program (GHABAP) presented in reference 10. Input to the GHABAP was facilitated by use of the configuration geometry program (GEMPAK) of reference 11. The paneling scheme is presented in figure 4.

All configurations tested and reported herein were input in the GHABAP, and the longitudinal, lateral, and directional force and stability characteristics were calculated utilizing the tangent-cone pressure distribution option on the body and the tangent-

wedge option on the wings (method 1). Other options, such as tangent cone only on the fuselage forebody and tangent wedge on the wing and body aft of the wing-fuselage junction, were tried (method 2). The Spalding-Chi turbulent-skin-friction method was incorporated into all calculations using an estimated model wall temperature of about 760°R. (See appendix A.) A limiting expansion pressure coefficient of 70 percent vacuum condition (i.e., $C_{p,\text{limit}} =$ $-1/M_{\infty}^2$) was utilized for all calculations. ref. 12.) The pressure p_{∞} was assumed on body base. The effects of wing leading and trailing edges and body nose bluntness were not included in the general drag-coefficient estimates but are estimated to be only about 0.00049 for the 60° swept wing and 0.00126 for the 0° swept wing.

Results and Discussion

Presented in this section are the experimental results of 14 tests of model configurations, including wing-body tests with seven leading-edge sweep angles, six tests with longitudinal wing translation on the body, and one body-alone test. These data are compared for variations with sweep, wing shift, and with hypersonic theory. The effects of wing airfoil geometry on pitching moments are examined, the isolated wing is studied by examining "secondary wing data," and the Hypersonic Isolation Principle is discussed.

Wing Sweep

The complete static longitudinal force and moment data for the wing-body configurations are presented in figure 5 for various leading-edge sweep angles (-30°) forward sweep to 60° aft sweep). The body was common to all tests and the wings had a common airfoil, aspect ratio, taper ratio, thickness ratio, span, and planform area. (See fig. 1 and table II.) Because of the nearly identical values of the coefficients, the force data were plotted using sliding vertical scales. The pitching-moment data were plotted in customary fashion and are discussed subsequently. An examination of figures 5(a) to 5(e) shows that the variation of force coefficients with sweep angle was small, considering the range of leadingedge sweep angles investigated, and the theoretical estimates were good to excellent for all configurations throughout the angle-of-attack range. The estimates of normal and lift forces and the lift-drag ratio showed better agreement with experiment at negative angles of attack and with higher sweep angles.

Wing leading-edge sweep angle had negligible effects on the longitudinal forces of the wing-body configurations through an angle-of-attack range from -12° to 10° . Excellent correlation between experiment and theory was possible for all wing leading-edge sweep angles from -30° to 60° from estimates made by the GHABAP utilizing the tangent-cone and tangent-wedge pressure options on the body and wing, respectively, and a limiting expansion pressure coefficient of $C_{p,\text{limit}} = -1/M_{\infty}^2$.

Wing Shift

The present paper includes a study of systematic longitudinal wing translation for each leading-edge sweep angle to first keep the location of the total wing mean aerodynamic chord \bar{c}_{tot} and the exposed mean aerodynamic chord \tilde{c}_{exp} at a common body station. (See fig. 3.) These particular reference body stations or wing locations were selected based on the \bar{c}_{tot} and $\bar{c}_{\rm exp}$ of the 60°-swept-wing baseline configuration and are designated in figure 5 by symbols. An aft shift of all wings having leading-edge sweep angles less than 60° was required to keep the $\tilde{c}_{\rm tot}$ and $\bar{c}_{\rm exp}$ at the common baseline body stations. (See fig. 3.) An examination of all force coefficients, experimental and calculated, in figures 5(a) to 5(e) shows that there was no effect of the rearward longitudinal shift of the wing. The maximum shift amounted to almost 17 percent $\tilde{c}_{\rm tot}$ for the test with the -30° swept wing. This longitudinal shift of the wing of up to 17 percent \bar{c}_{tot} had no effect on the measured or calculated forces of the present wing-body test configurations.

Pitching Moments

The pitching-moment coefficients for the various wing-body configurations investigated are plotted against angle of attack and lift coefficient, respectively, in figures 5(f) and 5(g). Experimental data and theory, presented separately for clarity, are shown for the wings in the forward position (i.e., with \bar{c}_{tot} at a constant body station) in the left-hand plots of figures 5(f) and 5(g) and for the aft position (i.e., with \bar{c}_{exp} at a constant body station) in the righthand plots of figures 5(f) and 5(g). It is particularly important to the present investigation that the experimental and theoretical pitching-moment curves varied with each change in wing sweep angle only when the wing was located longitudinally on the body with \bar{c}_{tot} at a constant body station. When the wings were located on the body with \bar{c}_{exp} at a constant body station, there was little variation of the pitching-moment curves with wing leading-edge sweep. Although the theory GHABAP underpredicted the pitching moments for all wing sweep angles tested, it correctly predicted the variations of pitch with sweep for the \bar{c}_{tot} tests and verifies the constant pitching-moment curve with wing sweep for the $\bar{c}_{\rm exp}$

tests. This is illustrative experimentally and theoretically of the Hypersonic Isolation Principle proposed in the Introduction and shows that regardless of sweep angle the exposed wing areas are equally effective in producing pitch. A study of these data shows that the experimental center of pressure on the exposed wing areas was essentially fixed for each angle of attack for the various sweep angles tested at about $0.495\tilde{c}_{\rm exp}$ as determined from wing-alone data (the difference between wing-body tests and body-alone tests, referred to herein as "secondary experimental wing data"). Theory on the isolated wing predicts the center-of-pressure location to be at about $0.432\bar{c}_{\rm exp}$. This difference between theory and secondary experimental data amounts to about $0.06\bar{c}_{\rm exp}$ and is probably caused by a variety of reasons, including wing-body interference, inaccuracy in the prediction, distribution of local pressures, unaccounted for tip losses, location of the wing behind the bow shock, and possibly the lack of consideration of boundary-layer-induced pressures. Boundarylayer buildup effectively alters the geometry of the aerodynamic surface and therefore the surface pressure distribution. This geometry change has not been estimated on the present wings but a study of airfoil thickness ratio is given in appendix B. Isolated wing tests would be necessary to adequately address this difference between theory and experiment. The scatter of the experimental data with sweep angle in the right-hand plots of figures 5(f) and 5(g) was attributed to either small changes in pitching moment due to wing sweep or mutual wing-body interference that may also vary with sweep or both. Such scatter was not shown in the longitudinal force coefficients, as discussed previously, but was evident in the directional stability data that is discussed subsequently. The GHABAP estimates therefore provide low and inadequate estimates of the magnitude of the pitching moments of the wing-body test configurations for all wing sweeps and wing locations.

60°-Swept-Wing Baseline Configuration

A comparison of GHABAP methods 1 and 2 of predicting the static longitudinal aerodynamics of the 60°-swept-wing baseline configuration is presented in figure 6. Using method 1 (tangent-cone pressure distribution option on the fuselage and tangent-wedge option on the wings), good to excellent predictions of normal, axial, lift, and drag forces and lift-drag ratio were obtained throughout the angle-of-attack range. Slightly better predictions were observed at negative angles of attack, particularly for the lift and the lift-drag ratio. Predictions of forces and of the lift-drag ratio for the body alone (fig. 7) are only fair and show the same trends as

those for the complete model. (See fig. 6.) That is, normal force, lift, and lift-drag ratio were overpredicted. Satisfactory predictions of pitching moments were, however, realized for the body alone. The body nose contour was designed using tangent-cone theory to provide zero normal force at $\alpha = 0^{\circ}$, and this was realized experimentally on the body alone. It is not understood why, for the wing-body configuration (complete model, fig. 6), the normal force was not zero at $\alpha = 0^{\circ}$, as the symmetrical sectioned wing was installed parallel to the longitudinal reference axis. Without wing-alone data, there can be no certainty, but the differences between the completemodel data and the theory were probably due in part to wing-body interference and poor fuselage predictions rather than the predicted wing increments.

Predictions of the 60° body-wing pitching moments left much to be desired. Underestimations for the complete model (fig. 6) amounted to a centerof-pressure shift of almost $0.05\bar{c}$. To investigate this variation, a somewhat unrealistic pressure distribution scheme was programmed. This scheme consisted of applying the tangent-cone option only on the body forward of the wing-fuselage junction and the tangent-wedge option on the aft fuselage and wing (method 2). The results of this calculation are shown in figure 6 by dashed lines. There is a marked improvement in the predictions of the pitching moment, but there is an accompanying overprediction of all forces. It may be inferred from this comparison that the selection of the computer program pressure distribution option was a partial cause of the pitchingmoment underprediction and that the selection of the model component on which to apply a particular pressure option is of equal importance. Although the present methods of analysis by the GHABAP do not provide satisfactory pitching-moment predictions for the 60°-swept-wing wing-body baseline configuration (fig. 6), satisfactory predictions were obtained for the body-alone configuration (fig. 7).

Wing-Body Interference Deduced From Secondary Wing Data

As previously mentioned, the determination of mutual wing-body aerodynamic interference would ideally be made through the use of at least three sets of experimental data, the wing-body combination tests, and the wing and body tested separately. The present study included the wing-body and body-alone tests, but no wing-alone tests; therefore, the secondary wing data (difference between the wing-body experimental data and the body-alone data) were used in place of the ideal wing-alone data. These secondary wing data contain, in addition to

the basic desired wing forces and moments, an unknown degree of mutual wing-body interference and a variation in magnitude due to the location of the wings. It was determined from schlieren photographs that 72 to 86 percent of exposed wing ($\Lambda = -30^{\circ}$ and 60°) was located behind the body nose shock, where variations in local dynamic pressure and flow angularity from the free-stream conditions would be expected to exist, particularly at angle of attack. With these known possible limitations, the results of subtracting the body-alone data from the wingbody data are presented in figure 8 and are compared with tangent-wedge calculations made using the GHABAP. Figure 8(a) shows that, at a positive value of α , the secondary wing axial-force coefficients were overestimated and that the normalforce and pitching-moment coefficients were underestimated at all angles of attack. It has been previously pointed out that the wing-body (fig. 6) and bodyalone (fig. 7) normal-force coefficients were overestimated, and, inasmuch as the present wing calculations did not account for tip losses, it was to be expected that the normal force would be overpredicted (refs. 7 and 13). However, figure 8 shows the normalforce coefficient to be underpredicted. It is therefore reasonable to assume that the secondary data of figure 8 were probably altered by mutual wing-body interference, which includes the effects of the region of variable dynamic pressure downstream of the nose shock.

In all instances, the normal-force coefficients were overestimated for a variety of wings at $M_{\infty} = 6.9$, particularly without tip correction. (See ref. 13.) Wing-alone data at $M_{\infty}=4.6$ (ref. 7) made possible the comparison that is shown in the inset of figure 8(a). Shown in the inset are the center-ofpressure locations and the normal-force coefficients for a series of AR = 2 wings of varying taper ratio λ . These wings did not have the constant thickness ratio of the present test wings, but the range of taper ratios tested straddled the present taper ratio of 0.25. As expected, tangent-wedge calculations of these isolated wings show an overestimation of the normal-force coefficients. Interpolation of these $M_{\infty} = 4.6$ data for $\lambda = 0.25$ indicated a difference between the measured and calculated center-ofpressure locations of $< 0.01\bar{c}$. The difference between the secondary wing data and the calculated values of $M_{\infty}=6.0$ were of the order of $0.04\bar{c}$. The centroid of the wing is located downstream of the configuration moment center, and any increase in local wing pressures, whether due to body interference or wing location behind the semiconical nose shock, increases the nose-down or negative pitching moment. The present theory does not take these factors into account. It may be concluded that the low predictions of normal-force and pitching-moment coefficients for the secondary wing data were due in part to mutual wing-body interference and in part to the wing location in the variable dynamic pressure region downstream of the body nose shock.

Static Lateral-Directional Stability

The variations of the lateral-directional stability of the wing-body configuration with wing leading-edge sweep are presented in figure 9, along with theoretical estimates made using the GHABAP. The experimental data were derived from the difference between measurements at 0° and 2° sideslip divided by 2° to obtain the slope of each component per degree. Tests were made only with the wing in the forward position.

It is shown in figure 9 that the side forces and the rolling moments were relatively insensitive to wing sweep when compared with the directional stability, which shows considerable sensitivity. All configurations are shown to be directionally unstable $(-C_{n_{\beta}})$, as might be expected for a configuration with no vertical surfaces, and to have negative dihedral effect $(+C_{l_{\beta}})$ throughout the angle-of-attack range. The variation of experimental directional stability with angle of attack was greatest for the -30° -swept-wing model and smallest for the 60°-swept-wing model. The theoretical estimates of the lateral-directional characteristics left much to be desired. The trends with angle of attack were approximated for the side force and rolling moments, but the methods predicted an opposite trend for the directional stability. The difference between theory and experiment was so great that the use of the theory, for any but the most preliminary of estimates, could not be recommended. The addition of vertical stabilizing surfaces would be expected to not only increase the directional stability but also decrease the negative dihedral effects. It may be concluded that the GHABAP is not satisfactory for estimating lateral-directional stability.

Hypersonic Isolation Principle

As stated in the Introduction, an assessment of the Hypersonic Isolation Principle was one of the objectives of the present study. This objective was accomplished when the theory and experimental data showed negligible changes of longitudinal and lateral forces with wide variations of wing sweep and moderate wing translation. (See sections entitled "Wing Sweep" and "Wing Shift".) Further realization of the validity of the Hypersonic Isolation Principle was apparent when nearly constant pitching-moment curves were observed with wing sweep angle when the \bar{c}_{exp}

and, hence the exposed-wing centroid of area, was held fixed at a constant body station. This constant pitching moment with wing sweep was predicted by the hypersonic impact type theory of the GHABAP, but the magnitudes of the pitching moments were underpredicted, as previously discussed. A more rigorous assessment was not possible because of the body nose shock interference effects on all test wings at all angles of attack. The area of the wing enclosed behind the shock varied for each sweep angle, and this difference contributed to the scatter in the pitching-moment data shown on the right-hand side of figures 5(f) and 5(g), as discussed in the pitchingmoment and wing-body interference sections. Although the body nose shock effects on the wing pressure distributions may be considered an interference effect, the interactions of body flow field and the wing flow field are yet to be sorted out experimentally. A proper assessment must await isolated wing tests and wing-body tests with the wing entirely downstream of the body nose shock.

Conclusions

An analysis of experimental data for a wing-body configuration and components with interchangeable variable sweep and longitudinally translatable wings at a free-stream Mach number of about 6 and a free-stream Reynolds number (based on body length) of 17.9×10^6 leads to the following conclusions:

- 1. Good to excellent predictions of longitudinal forces (normal, axial, lift, and drag) and lift-drag ratio were obtained throughout the angle-of-attack range on all wing-body configurations tested by utilizing the tangent-cone theory on the body and the tangent-wedge theory on the wings, and by limiting the expansion pressure coefficient to 70 percent vacuum conditions.
- 2. Unsatisfactory predictions of the magnitude of the pitching-moment coefficients were obtained on all the wing-body configurations tested with the simplified tangent-cone/tangent-wedge analysis procedure provided by the Gentry Hypersonic Arbitrary-Body Aerodynamic Program (GHABAP). This is the result of the program not accounting for mutual wingbody interference, for wing tip losses, for the partial location of the wings in the region behind the bow shock where variations in local dynamic pressure may be expected, and for the lack of consideration of turbulent-boundary-layer induced pressures. For these reasons, higher than expected values of experimental normal force and pitching moment were exhibited by the secondary wing data (the difference between wing-body and body-alone experimental data).

- 3. Fair predictions of aerodynamic forces and lift-drag ratio and good predictions of pitching moments were obtained on the body alone by utilizing the tangent-cone theory and limited expansion pressure coefficients in the GHABAP.
- 4. Analytic studies showed that for Mach numbers above about 2, the center of pressure of a solitary wing is primarily a function of thickness ratio and secondarily a function of airfoil section, sweep, taper ratio, Mach number, and angle of attack. Any increase in thickness ratio of the present wedge-slabwedge wing airfoil would have had a destabilizing effect on the complete configuration.
- 5. The hypersonic impact methods, as utilized by the GHABAP, are not satisfactory for estimating lateral-directional stability.
- 6. The variations of the experimental longitudinal force coefficients with leading-edge sweep or wing shift were small, and there were no variations of

the calculated force coefficients with either geometric change.

- 7. Only the exposed wing (wetted area) was effective in producing aerodynamic forces and pitching moments at hypersonic speeds, and the mean aerodynamic chord of the exposed wing should be used as the design reference.
- 8. The "Hypersonic Isolation Principle" was verified experimentally by showing the independence of the longitudinal and lateral forces and pitching moments from wing leading-edge sweep variations when the exposed wing mean aerodynamic chords, hence the exposed wing centroids of area, were located at a fixed body station.

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Appendix A Spalding-Chi Turbulent Skin Friction

The semiempirical procedure for the calculation of turbulent skin friction by Spalding and Chi has been shown to provide very good agreement with experiment for adiabatic wall conditions (ref. 14). The model wall temperatures of the present tests were estimated to be about 760°R, and the tunnel stagnation temperature was about 870°R. These conditions resulted in a wall-to-stagnation temperature ratio of 0.874; this ratio is not greatly different from the generally accepted adiabatic value of 0.89. The Spalding-Chi method was therefore not only the method of choice but was also available as an option in the GHABAP. A plot of the variations of the average Spalding-Chi turbulent-skin-friction coefficients with wall-to-stagnation temperature ratio and Reynolds number are presented in the upper part of figure 10 for M=6. The variations with Mach number and Reynolds number for the adiabatic wallto-stagnation temperature ratio of 0.89 are shown in the lower part of figure 10. Plotted on these figures are the Reynolds numbers, based on various dimensions of the test model, which vary from about 1.55×10^6 for the wing tip to 17.9×10^6 for the body. This wide range of Reynolds numbers may well have encompassed laminar flow at the lower values and a high percentage of turbulent flow at the higher values of Reynolds number and an unknown percentage of transitional flow on both wings and body. Although the assumption of all turbulent skin friction gave good estimates of drag and lift-drag ratio on the present wing-body configuration, it is more likely that there were regions of laminar, transitional, and turbulent skin friction on the model and that the experimental average was approximately equal to the estimated turbulent values. Reference 15 is suggested for additional charted values of Spalding-Chi skin friction for other Mach numbers and wallto-stagnation temperature ratios.

Appendix B

Effects of Wing Airfoil Geometry on Pitching Moments

To gain a better understanding of the effects of component geometry on lift and pitching moments a study was instigated to determine the effects of variations of wing airfoil thickness ratio on the estimated pitching moments. This study consisted of making two-dimensional inviscid calculations on a series of wedge-slab-wedge airfoils having thickness ratios of 0 percent to 10 percent chord at $\alpha = 3^{\circ}$ at M = 6. The results of the study are presented in figure 11 and show a destabilizing shift of the center of pressure with thickness ratio from the 50 percent chord location for the 0 percent thick airfoil to about the 31 percent chord location for the 10 percent thick wing. These estimates were verified at Mach numbers up to 5 by charts in reference 1, which also showed a stabilizing effect of angle of attack. This forward destabilizing shift in center of pressure with increasing thickness ratio is readily understood when consideration is given to the increased pressures on

the forward-wedge compression surface of the airfoil and the decreased pressures on the rear-wedge expansion surface. The stabilizing effect of angle of attack is due to an increase in pressure on the rear-wedge surface with angle of attack. At very high angles of attack ($\alpha \approx 90^{\circ}$) this increase in pressure results in a center-of-pressure shift rearward to the 50 percent chord location. In addition to the center-of-pressure shift, increased increments of normal and axial force were obtained which also contribute to the longitudinal stability of the present wing-body configuration. This increased stability is the result of the moment reference location being ahead of the wing center of pressure and above the wing chordline. For Mach numbers above about 2, it may be concluded that hypersonic theory predicts that the center of pressure of a solitary wing with a sharp leading edge is primarily a function of the thickness ratio and secondarily a function of angle of attack, airfoil section, sweep, Mach number, and taper ratio. Also, any increase in wing thickness ratio of a wedge-slab-wedge airfoil would have a destabilizing effect on the overall configuration longitudinal stability.

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TABLE I. NOSE DIMENSIONS

[Reference fig. 1]

X, in.	r_1 , in.	r_2 , in.	h, in.	ΔZ , in.
0.0000	0.0000	0.0000	0.0000	0.3000
.5688	.1336	.0354	.3524	.2477
1.1376	.2203	.0584	.5813	.2137
1.7064	.2927	.0776	.7723	.1853
2.2752	.3558	.0944	.9388	.1606
3.4128	.4620	.1225	1.2191	.1189
4.5504	.5478	.1453	1.4454	.0853
5.6880	.6170	.1636	1.6279	.0582
6.8256	.6718	.1781	1.7724	.0368
7.9632	.7133	.1891	1.8821	.0205
9.1008	.7425	.1969	1.9591	.0090
10.2384	.7599	.2015	2.0048	.0023
11.3760	.7656	.2031	2.0200	.0000

TABLE II. TYPICAL WING GEOMETRY

Span, in.					12.6
Planform area, in ²					
Aspect ratio					2.0
Taper ratio					
Thickness ratio					0.03
Centerline root chord, in.					
Exposed root chord, in					8.815
Tip chord, in					2.425

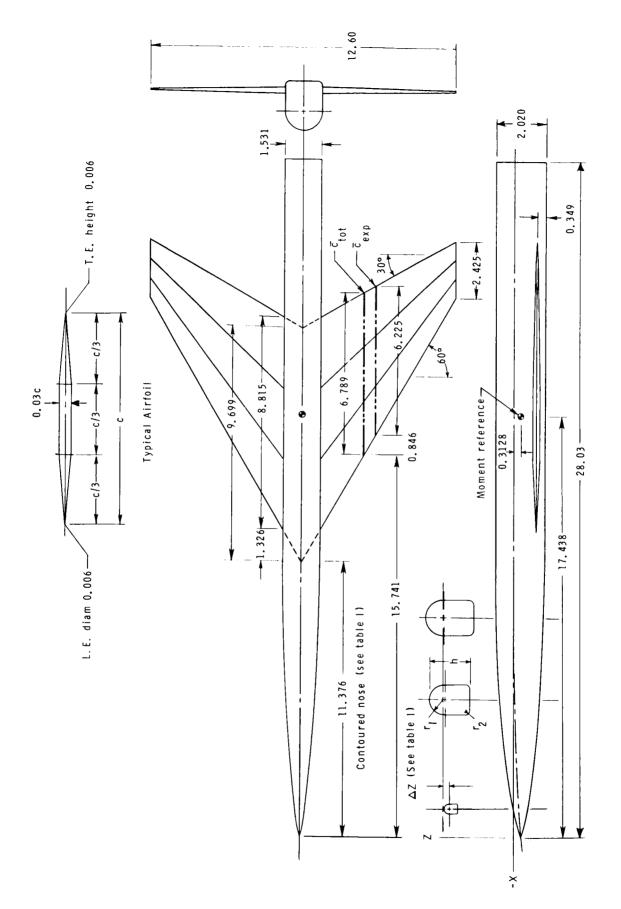


Figure 1. Details of 60°-swept wing-body baseline wind-tunnel model. All dimensions in inches.

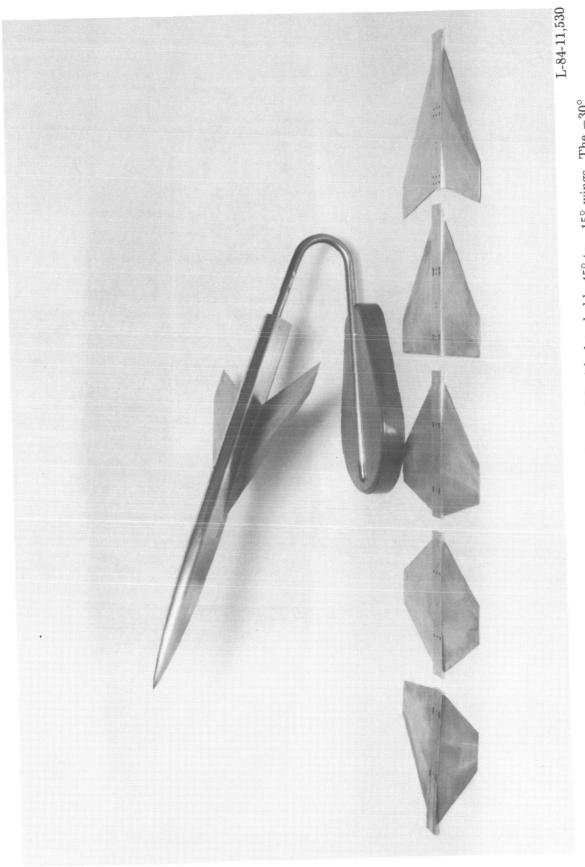


Figure 2. Photograph of 60° -swept wing-body baseline model with detachable 45° to -15° wings. The -30° swept test wing was the 60° swept wing reversed.

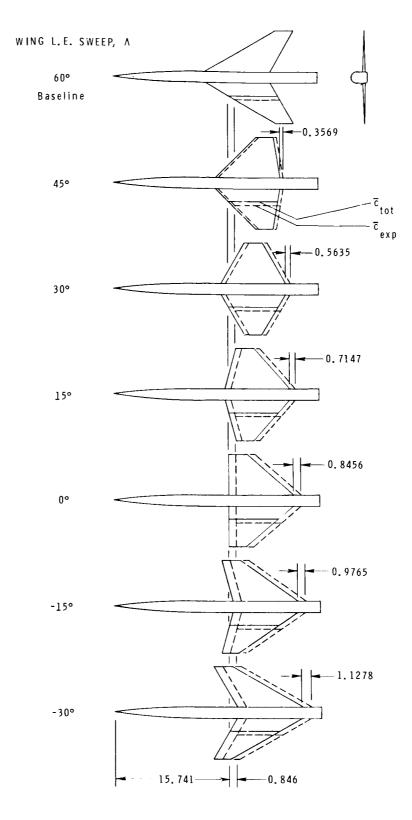


Figure 3. Wing translation required to hold \bar{c} at a fixed body station. All linear dimensions in inches.

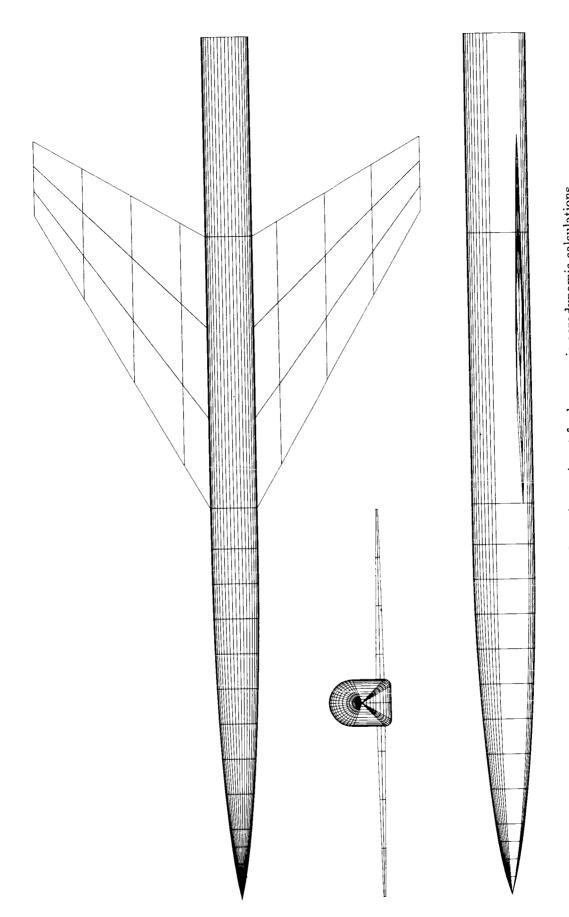


Figure 4. Paneling scheme of configuration as input for hypersonic aerodynamic calculations.

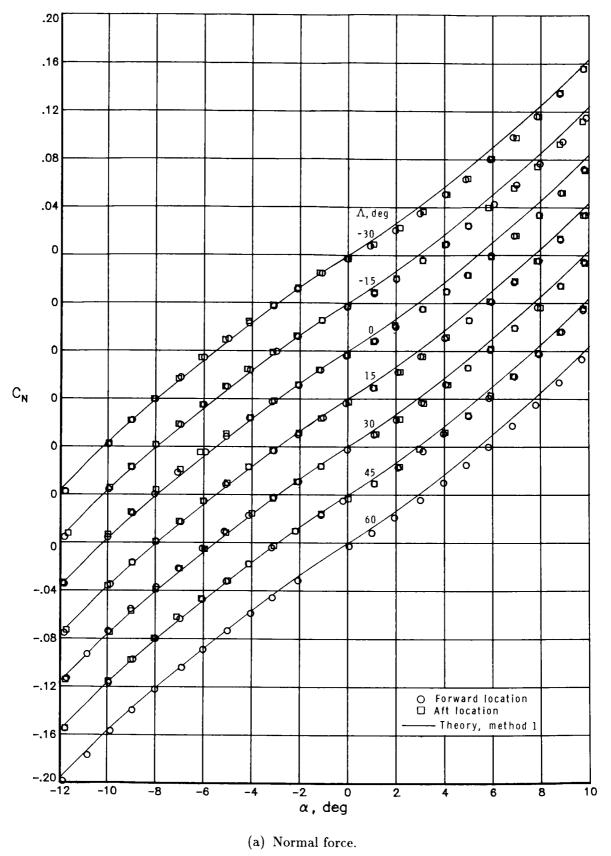


Figure 5. Comparison of static longitudinal force and moment coefficients for fore and aft wing locations and theory. $M_{\infty} = 5.98; R_l = 17.9 \times 10^6$.

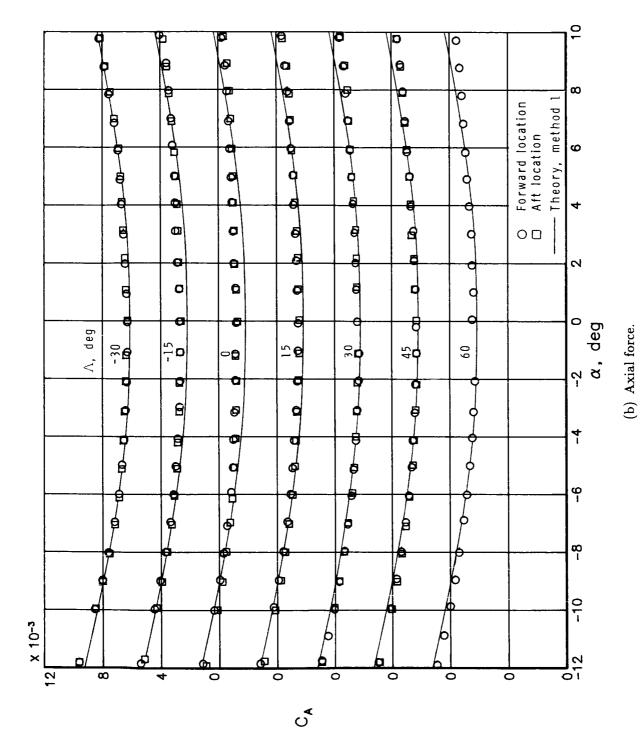


Figure 5. Continued.

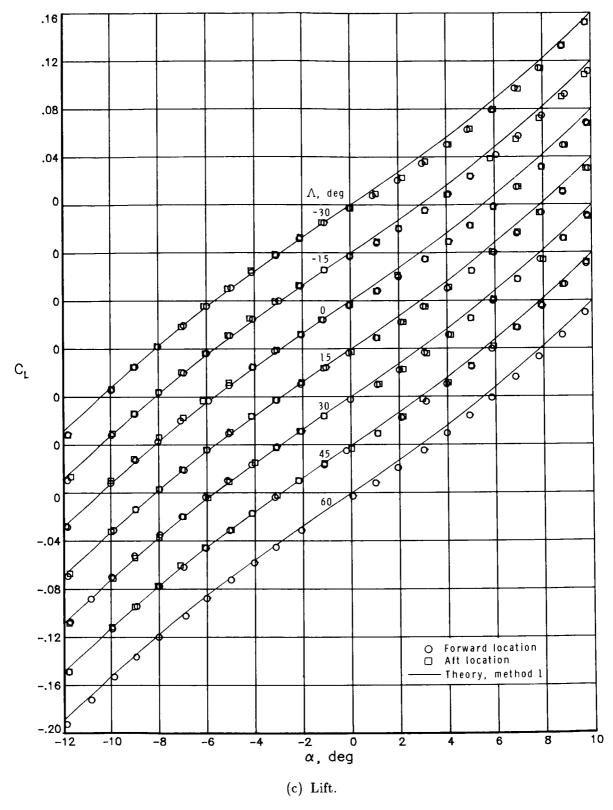


Figure 5. Continued.

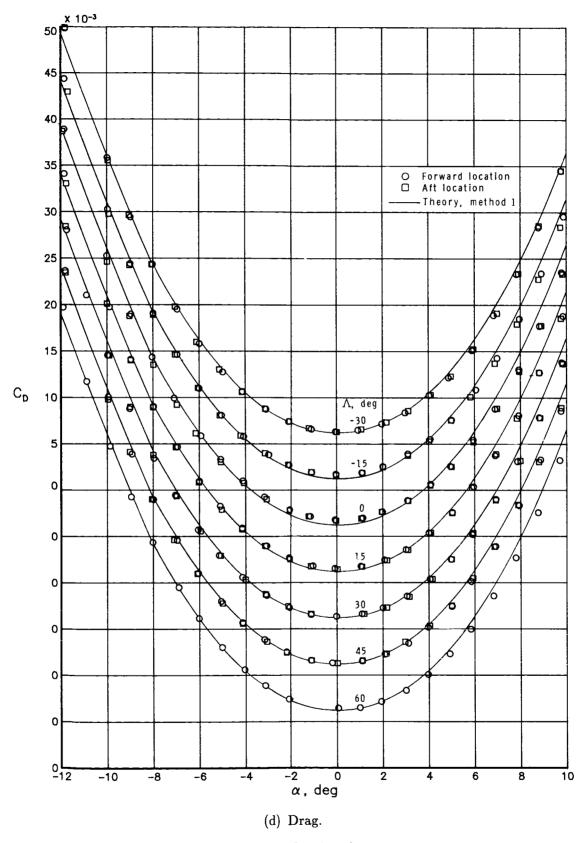
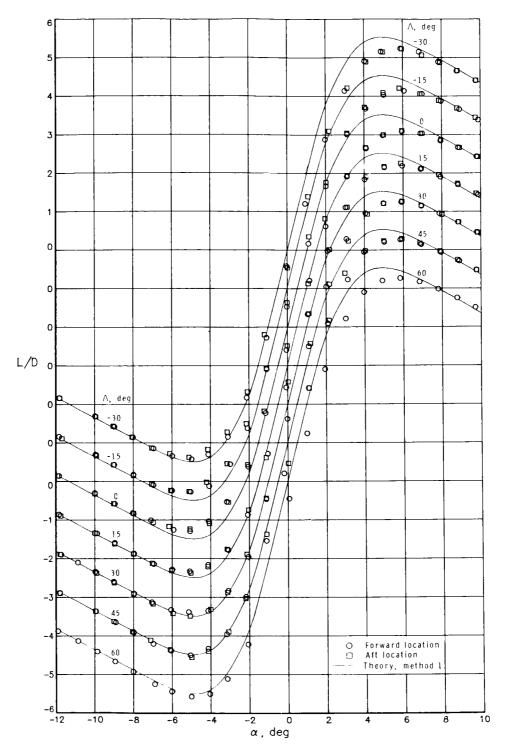


Figure 5. Continued.



(e) Lift-drag ratio.

Figure 5. Continued.

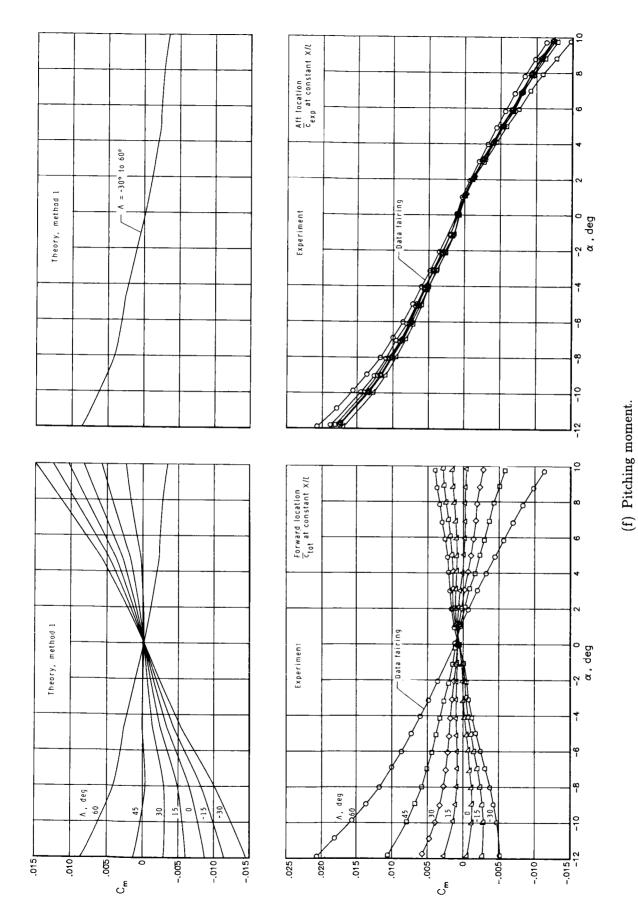
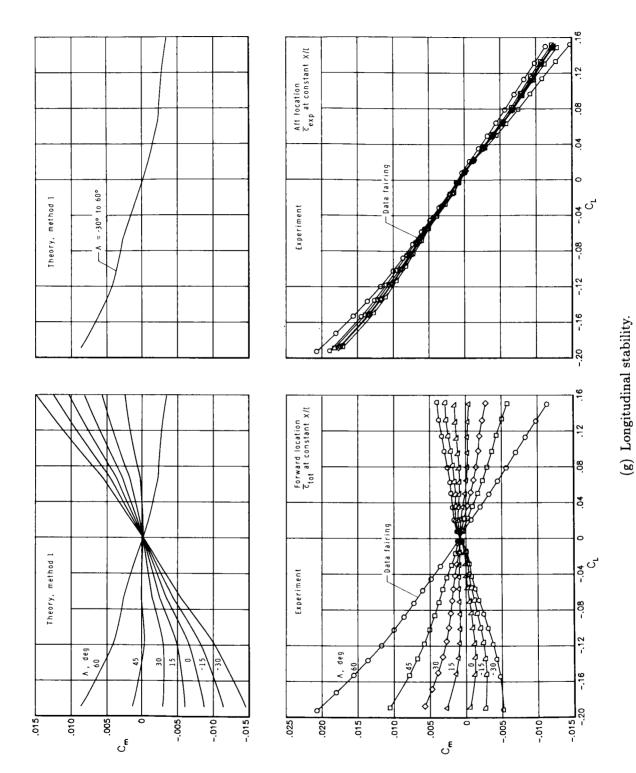
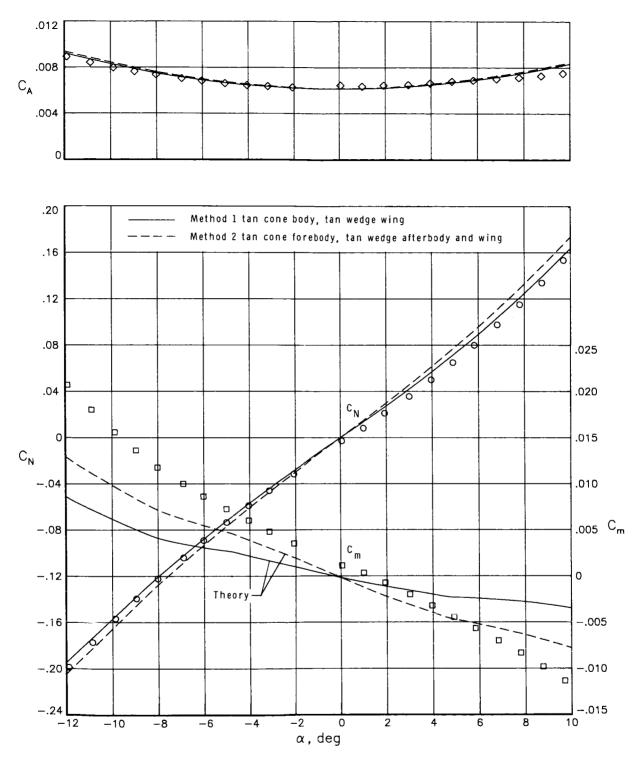


Figure 5. Continued.

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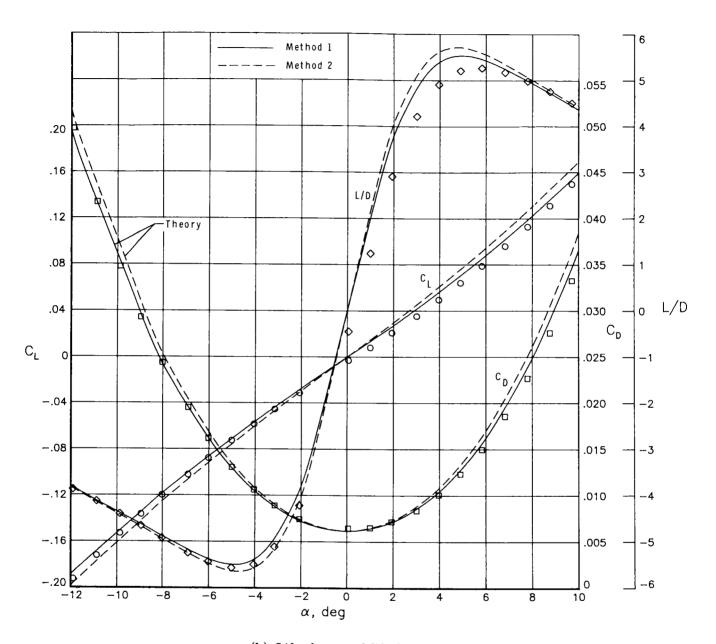


(g) Longitudinal stability Figure 5. Concluded.



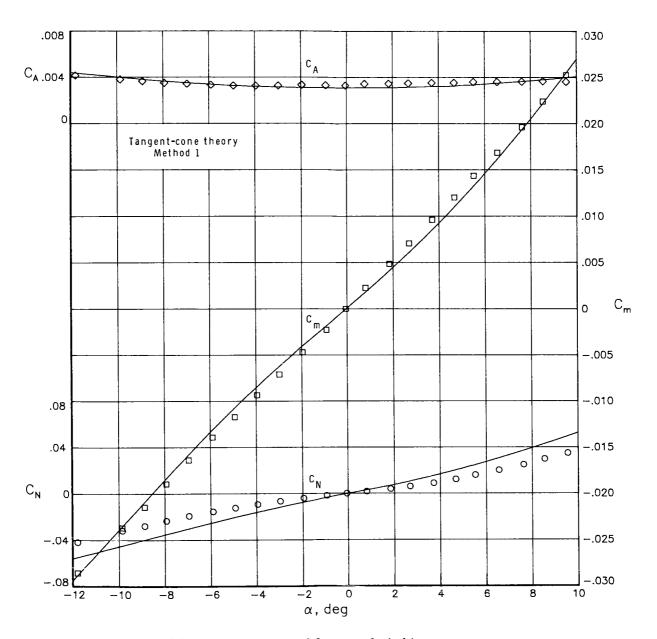
(a) Normal force, axial force, and pitching moment.

Figure 6. Comparison of methods of predicting static longitudinal aerodynamics of 60° -swept-wing baseline configuration. $M_{\infty}=5.98; R_l=17.9\times 10^6$.



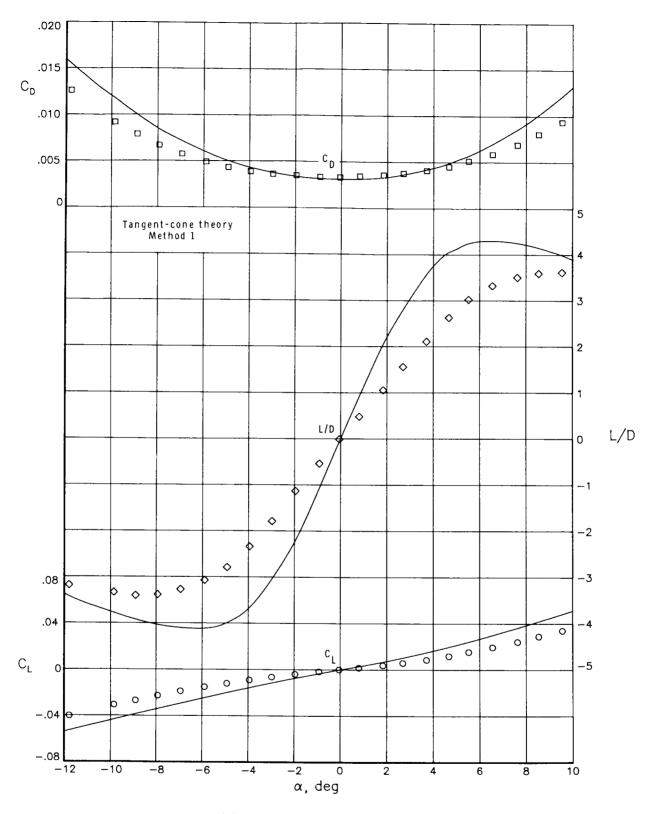
(b) Lift, drag, and lift-drag ratio.

Figure 6. Concluded.



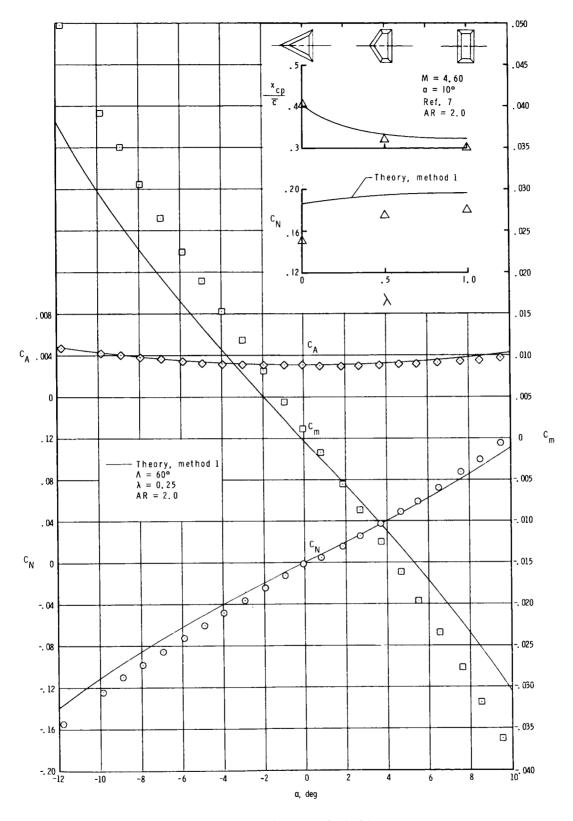
(a) Normal force, axial force, and pitching moment.

Figure 7. Comparison of static longitudinal force and moment coefficients of the body alone with theory. $M_{\infty}=5.98; R_l=17.9\times10^6.$



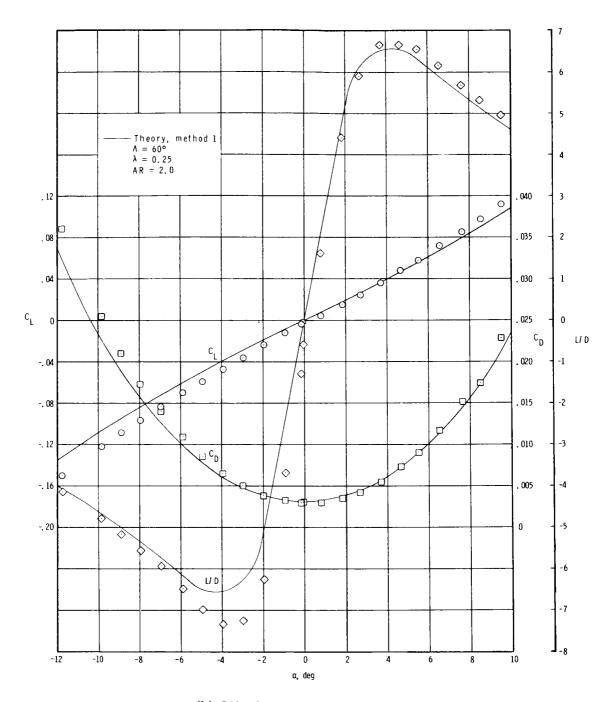
(b) Lift, drag, and lift-drag ratio.

Figure 7. Concluded.



(a) Normal force, axial force, and pitching moment.

Figure 8. Comparison of static longitudinal force and pitching-moment coefficients of secondary wing-alone data and theory. $M_{\infty}=5.98; R_l=17.9\times 10^6.$



(b) Lift, drag, and lift-drag ratio.

Figure 8. Concluded.

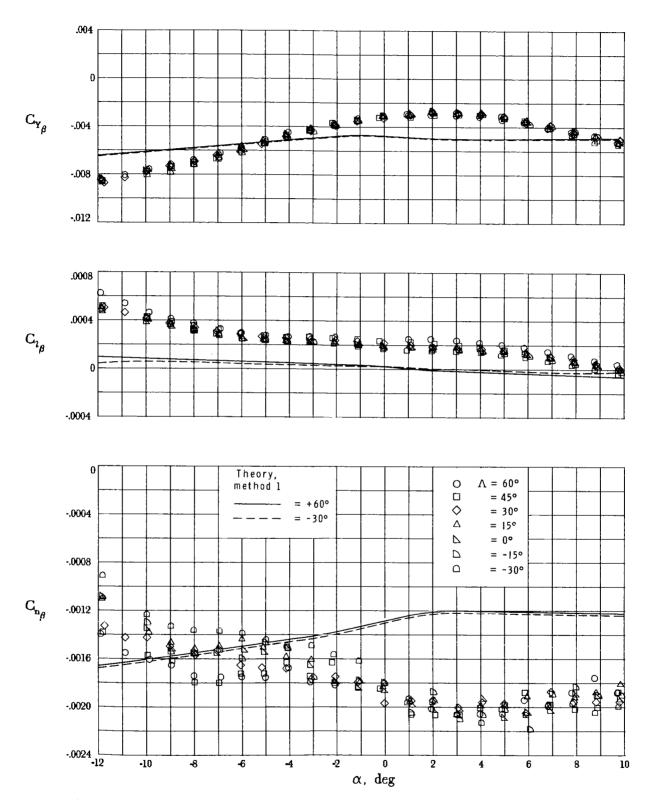


Figure 9. Lateral-directional stability characteristics of test configurations and comparison with theory. $M_{\infty} = 5.98; R_l = 17.9 \times 10^6;$ wing in forward position.

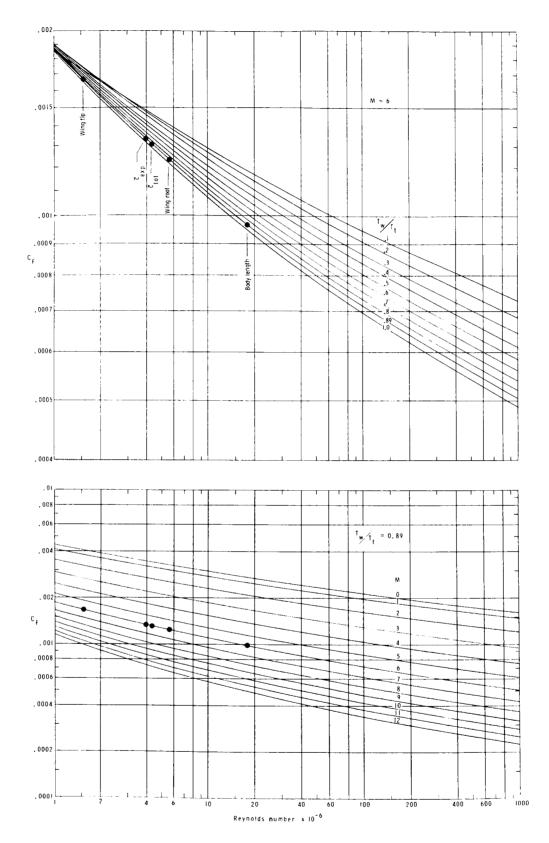


Figure 10. Spalding-Chi average turbulent skin friction on one side of flat plate. $\alpha=0^\circ$.

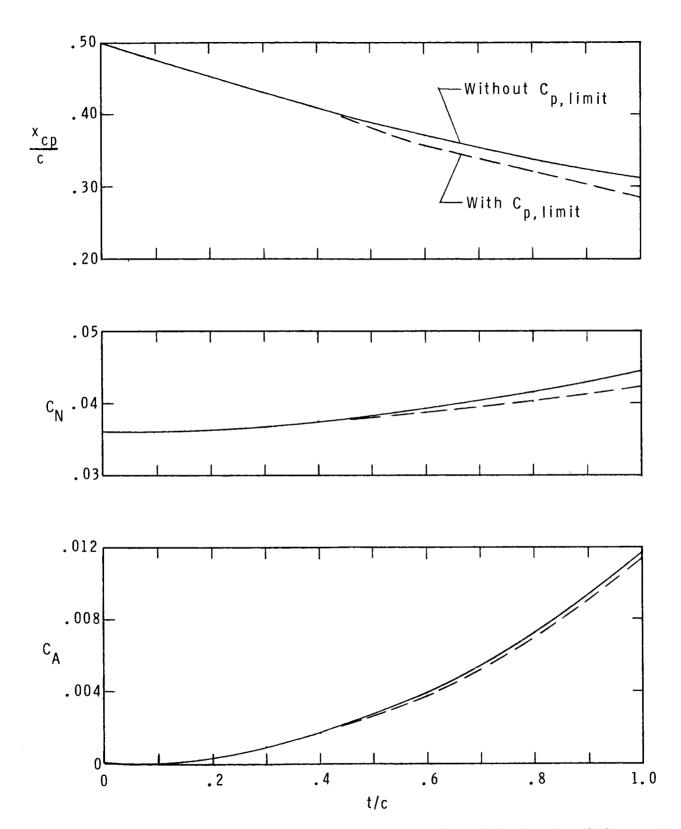


Figure 11. Two-dimensional inviscid aerodynamics on wedge-slab-wedge airfoils of varying thickness ratios. $\alpha=3^\circ; M_\infty=6.$

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